OPERATOR-STABLE PROBABILITY DISTRIBUTIONS ON VECTOR GROUPS

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1. **Introduction.** An operator-stable probability distribution in a group G is a limit law arising, roughly speaking, from affine modification of the partial sums of a sequence of independent identically distributed G-valued random variables. This paper is concerned with a more palpable description of an operator-stable distribution in the case where G is a vector group; i.e. the topological group underlying a d-dimensional real vector space.

The first step is to reduce the problem to that of finding those probability measures λ , all of whose convolution powers are of the same type; i.e. for each integer $k \ge 1$, there is an automorphism B_k of G such that λ^k is a translation of the measure $\lambda \circ B_k^{-1}$. It is then shown that λ is operator-stable if and only if for each t>0, λ^t is a translation of the measure $\lambda \circ [\exp(\log t \cdot B)]^{-1}$, for an automorphism B of G characterized by conditions on the spectrum of B regarded as a linear operator on a vector space.

2. Notation and definitions. Throughout this paper, we denote by V a d-dimensional vector group. In several proofs, we shall use the same symbol to denote the same group with the additional structure of a vector space, or even an inner product space. Denote by $\mathscr{P} = \mathscr{P}(V)$ the set of probability measures on V. With the topology of weak convergence, and multiplication defined by convolution, \mathscr{P} becomes a topological semigroup. We denote convolution of two measures λ , μ by $\lambda * \mu$, and the nth convolution power of λ by λ^n .

By V^{\wedge} , we mean the character group of V, "identified" with the dual vector space of the vector space V. In the sequel, x will denote the generic element of V and y the generic element of V^{\wedge} . Let (x, y) denote the bilinear pairing of V and V^{\wedge} brought about by y acting as a linear functional on x. As a group character, y acts on x according to $\exp i(x, y)$. The characteristic function of a measure $\lambda \in \mathcal{P}(V)$ is defined by

$$\varphi(y) = \lambda^{\hat{}}(y) = \int_{V} \exp i(x, y) \lambda(dy).$$

Given $\lambda \in \mathcal{P}(V)$, we define $\lambda^- \in \mathcal{P}(V)$ by $\lambda^-(E) = \lambda(-E)$. The mapping $\lambda \to \lambda^-$ is an involutive automorphism of \mathcal{P} . It is easy to check that $\lambda^- \cap \equiv \lambda^-$, the last

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bar denoting the complex conjugate. The measure λ is called symmetric if and only if $\lambda = \lambda^-$. For any $\lambda \in \mathcal{P}$, the measure $\lambda^0 = \lambda * \lambda^0$ is symmetric, and is called the symmetrization of λ .

Let $H(\lambda) = \{ y \in V^{\wedge} \mid \lambda^{\wedge}(y) = 1 \}$. It is easy to see that $H(\lambda)$ is a closed subgroup of V^{\wedge} . Note that $\{ y \in V^{\wedge} \mid |\lambda^{\wedge}(y)| = 1 \} = H({}^{\circ}\lambda)$ is a closed subgroup of V^{\wedge} containing $H(\lambda)$.

Denote by $S(\lambda)$ the support of the measure $\lambda \in \mathcal{P}(V)$, viz., the smallest closed set F in V with $\lambda(F) = 1$. The relation $S(\lambda * \mu) = \operatorname{Cl}(S(\lambda) + S(\mu))$ is well known. We call a measure $\lambda \in \mathcal{P}$ full if and only if $S(\lambda)$ is not contained in any (d-1)-dimensional hyperplane of V. If λ is not full, it is called deficient.

PROPOSITION 1. $\lambda \in \mathcal{P}(V)$ is a full measure if and only if $H(^{\circ}\lambda)$ does not contain a 1-dimensional subgroup of V^{\wedge} .

Proof. Firstly, λ is full if and only if ${}^{\circ}\lambda$ is full. If $S({}^{\circ}\lambda) \subset X$, a (d-1)-dimensional subspace of V, then

$$^{\circ}\lambda^{\hat{}}(y) = \int_{X} \exp i(x, y)^{\circ}\lambda(dx)$$
$$= 1 \quad \text{if } y \in X^{\perp} = \{ y \in V^{\hat{}} \mid (x, y) = 0, \, \forall x \in X \},$$

and X^{\perp} is a 1-dimensional subspace of V^{\wedge} . Conversely, if $H(^{\circ}\lambda)$ contains a 1-dimensional subspace Y of V^{\wedge} , then $\int_{V} \exp i(x, y)^{\circ} \lambda(dx) = 1$ for all $y \in Y$ implies $\exp i(x, y) = 1$, $^{\circ}\lambda$ -almost everywhere, for all $y \in Y$, which implies

$$^{\circ}\lambda\{x\mid \exp i(x,y)=1\}=1\quad \text{for all }y\in Y$$

so that

$$S(^{\circ}\lambda) \subset \{x \mid (x, y) = 0 \mod 2\pi \text{ for all } y \in Y\} = \{x \mid (x, y) = 0 \text{ for all } y \in Y\} = Y^{\perp},$$
 a $(d-1)$ -dimensional subspace of V .

We mention that the set \mathscr{F} of full measures in $\mathscr{P}(V)$ is an open subsemigroup of \mathscr{P} .

Let us denote by End V the ring of continuous endomorphisms of the group V, identified with the ring of linear transformations of the vector space V. Let Aut V denote the group of continuous automorphisms of V, identified with the group Gl (V) of nonsingular linear transformations of the vector space V. For any $A \in \text{End } V$ and $\lambda \in \mathcal{P}(V)$, let $A\lambda$ denote the measure $A\lambda(F) = \lambda(A^{-1}(F))$, F a Borel subset of V. If $A \in \text{Aut } V$ and $a \in V$, we call the mapping $\lambda \to A\lambda * \delta(a)$ an affine transformation, $\delta(a)$ denoting the point mass at a. If instead $A \in \text{End } V \sim \text{Aut } V$, the mapping will be called singular affine. The set of affine transformations (A, a) is denoted by Aff V. If X is a V-valued random variable having distribution μ , then clearly, AX + a has distribution $A\lambda * \delta(a)$.

It is not difficult to verify that for any bounded continuous function f on V,

$$\int_{\mathcal{V}} f d(A\lambda) = \int_{\mathcal{V}} f \circ A d\lambda,$$

and that $S(A\lambda) = AS(\lambda)$, $(AB)\lambda = A(B\lambda)$, $A(\lambda * \mu) = A\lambda * A\mu$ and $(A\lambda)^{\hat{}}(y) = \lambda^{\hat{}}(A^*y)$, where A^* denotes the adjoint map of $V^{\hat{}} \to V^{\hat{}}$ induced by the bilinear pairing (\cdot, \cdot) ; i.e. $(Ax, y) \equiv (x, A^*y)$. We give End V the compact-open topology as a set of functions from V to V. This topology is equivalent to the norm topology of End V as a space of linear operators on V, when V is provided with a vector norm. It is easy to check that the mapping $\langle A, \lambda \rangle \to A\lambda$ of End $V \times \mathcal{P}(V) \to \mathcal{P}(V)$ is jointly continuous. We define an equivalence relation in $\mathcal{P}(V)$ by writing $\lambda \sim \mu$ if and only if there is an affine transformation (A, a) such that $\lambda = A\mu * \delta(a)$. The measures λ , μ are then said to be of the same type, and an equivalence class of measures is called a type. Clearly, random variables x and Ax + a will have distributions of the same type.

3. Statement of the problem. In terms of random variables, the problem we study is enunciated as follows: suppose that $\{x_n\}$ is a sequence of V-valued random variables with common distribution μ , and assume that the terms of the sequence are mutually independent; assume, further, that (A_n, a_n) is a sequence of affine transformations of V such that the distribution of $A_n(x_1 + \cdots + x_n) + a_n$ converges to a measure $\lambda \in \mathcal{P}(V)$; what can be said about the limit measure λ ?

Converting this to a problem involving only measures, we ask which measures λ can arise as limits of sequences $A_n\mu^n * \delta(a_n)$.

Our aim is to characterize those λ which are full and are such limits—denote by $\mathscr S$ the class of such measures. For reasons which do not become clear until the problem is posed in a different form, $\mathscr S$ is called the class of operator-stable measures on V. It is clear that $\mathscr S$ is invariant under affine transformations.

We refer the reader to Feller [1] for an account of the class $\mathscr S$ when V reduces to the real line. It is possible in this case to give an explicit formula for the characteristic function of a stable distribution. In fact (Feller [1, p. 542]) any such characteristic function $\lambda^{\hat{}}$ must have the form $\lambda^{\hat{}}(y) = \exp(a\psi_{\alpha,\delta}(y) + iby)$, where $0 < \alpha \le 2$, $-1 \le \delta \le 1$, and

$$\psi_{\alpha,\delta}(y) = -|y|^{\alpha} [1 - i \operatorname{sgn} y \, \delta \tan \pi \alpha/2], \qquad \alpha \neq 1,$$

= -|y|[1 + i \text{sgn} y \delta \log |y|], \qquad \alpha = 1.

In particular, $\lambda^{-t}(y) = \lambda^{-t}(t^{1/\alpha}y)$ exp ib(t)y, t > 0 where b(t) is real. It is easily seen that if $\alpha \neq 1$, there exists b such that $\mu = \lambda * \delta(b)$ satisfies $\mu^{-t}(y) = \mu^{-t}(t^{1/\alpha}y)$ but if $\alpha = 1$, it is not generally possible to make such a centering, and b(t) has the form b(t) = ct log t. These results are obtained from the fact that the Khintchine-Lévy measure M (see next paragraph) of a stable distribution must be given by $M\{[x,\infty)\}$ = $cpx^{-\alpha}$, $M\{(-\infty, -x]\} = cqx^{-\alpha}$ where $c \geq 0$, p+q=1, $p \geq 0$ and $q \geq 0$.

All that has been done so far in the multi-dimensional case is to find limits of distributions of sequences $A_n(x_1 + \cdots + x_n) + a_n$ where A_n is a multiple of the identity operator. By the same techniques as in the one-dimensional case, one finds the Khintchine-Lévy representing measures as mixtures of one-dimensional K-L measures for stable distributions concentrated in rays starting at the origin.

Our results will provide analogues of these facts, except that an explicit representation for a general operator-stable characteristic function does not seem possible.

4. The Khintchine-Lévy formula. A stable distribution is infinitely divisible and a major tool in the analysis of $\mathscr S$ will be the multi-dimensional form of the Khintchine-Lévy representation. The form we use is a slight modification of the original Lévy [4] version, and we state it as

PROPOSITION 2 (KHINTCHINE-LÉVY). To an infinitely divisible measure $\lambda \in \mathcal{P}(V)$, there corresponds a triple (c, ϕ, M) consisting of an element $c \in V$, a nonnegative quadratic form ϕ on V and a nonnegative Radon measure M on the locally compact space $V \sim \{0\}$ satisfying

- (i) M is finite off every neighborhood of 0, and
- (ii) $\int_{K\sim\{0\}} \|x\|^2 M(dx) < \infty$ for every compact subset K of V, $\|\cdot\|$ being any vector norm on V, such that

$$\lambda^{\hat{}}(y) = \exp \left\{ i(c, y) - \phi(y) + \int_{V \sim \{0\}} [\exp i(x, y) - 1 - i(\tau(x), y)] M(dx) \right\}.$$

Here, $\tau: V \to V$ is any continuous function satisfying

- (a) $\tau(x) = x + O(||x||^2) (x \to 0)$, and
- (b) τ is bounded.

A change in the function τ produces only a change in the term c.

For uniqueness, we know that if, for j=1, 2,

$$\psi_{j}(y) = i(c_{j}, y) - \phi_{j}(y) + \int_{V \sim \{0\}} [\exp i(x, y) - 1 - i(\tau_{j}(x), y)] M_{j}(dx)$$

and $\psi_1(y) = \psi_2(y)$ for all $y \in V^{\hat{}}$, then $\phi_1 = \phi_2$ and $M_1 = M_2$. If, further, $\tau_1 = \tau_2$, then $c_1 = c_2$.

We describe this representation by saying that λ has representing triple (c, ϕ, M) . Any nonnegative Radon measure M on $V \sim \{0\}$ satisfying (i) and (ii) will be called a K-L measure. Note that the element c determines merely a translation of λ , and ϕ determines the Gaussian component.

The next proposition is pure calculation, and sets out the manner in which the representing triple changes with an affine transformation of λ .

PROPOSITION 3. If λ is infinitely divisible in $\mathcal{P}(V)$ and has representing triple (c, ϕ, M) , and if $A \in \text{Aut } V$ and $a \in V$, then the representing triple of $A\lambda * \delta(a)$ is $(c', \phi \circ A^*, AM)$ for some $c' \in V$.

Proof. In the calculation, it is only necessary to note that if τ satisfies (a) and (b) of Proposition 2, then so does the function $A \circ \tau \circ A^{-1}$.

Finally, if λ is infinitely divisible with representing triple (c, ϕ, M) and t > 0, we let λ^t denote the tth power of λ ; viz., the infinitely divisible measure with representing triple $(tc, t\phi, tM)$. The semigroup $\{\lambda^t \mid t > 0\}$ is then weakly continuous.

5. Reduction of the problem. The following lemma is used repeatedly in the sequel. It is a generalization of a lemma which is well known in the one-dimensional set-up (see e.g. Feller [1, p. 246, Lemma 1]).

PROPOSITION 4 (THE COMPACTNESS LEMMA). Suppose that for $n=1, 2, ..., \lambda_n \in \mathcal{P}(V)$, (A_n, a_n) is an affine transformation, and assume that

- (i) $\lambda_n \to \lambda \in \mathcal{P}(V)$,
- (ii) $A_n \lambda_n * \delta(a_n) \to \mu \in \mathscr{P}(V)$.

Then, if λ and μ are full in V, the set $\{A_n \mid n=1, 2, \ldots\}$ is precompact in Aut V, $\{a_n \mid n=1, 2, \ldots\}$ is precompact in V, and if A and a are limit points in these respective sets, then $A\lambda * \delta(a) = \mu$.

In other words, if for $n = 1, 2, ..., \lambda_n \sim \mu_n$, if $\lambda_n \to \lambda$, $\mu_n \to \mu$ and λ and μ are full, then $\lambda \sim \mu$.

Proof. Let $\langle \cdot, \cdot \rangle$ be an inner product on V, and let $||x||^2 = \langle x, x \rangle$. If it is possible to prove that

- (A) $\{a_n \mid n=1, 2, \ldots\}$ is bounded in V, and
- (B) $\{||A_n|| \mid n=1, 2, ...\}$ is bounded in R,

then any sequence $\{n_k\}$ of positive integers will have a subsequence $\{n'_k\}$ such that $a_{n'_k}$ converges to an element a of V, and $A_{n'_k}$ converges to an element E of End V. By joint continuity,

$$A_{n!}\lambda_{n!} * \delta(a_{n!}) \to E\lambda * \delta(a)$$
 as $k \to \infty$.

But the left side converges to μ , so $\mu = E\lambda * \delta(a)$. Since $S(\mu) = ES(\lambda) + a$ is not contained in a (d-1)-dimensional hyperplane, E must be invertible, so that all limit points of $\{A_n \mid n=1, 2, \ldots\}$ are in Aut V, showing $\{A_n \mid n=1, 2, \ldots\}$ to be precompact in Aut V. It suffices, therefore, to prove (A) and (B).

We start with (B). Firstly, the conditions (i) and (ii) imply that ${}^{\circ}\lambda_n \to {}^{\circ}\lambda$ and $A_n({}^{\circ}\lambda_n) \to {}^{\circ}\mu$, where ${}^{\circ}\lambda$ and ${}^{\circ}\mu$ are full. In proving (B), we may therefore assume that $a_n = 0$ for all n. With this assumption in force temporarily, we shall assume, for purposes of obtaining a contradiction, that $\{\|A_n\| \mid n=1,2,\ldots\}$ is not bounded.

Let us choose a fixed orthonormal basis for the inner product space $(V, \langle \cdot, \cdot \rangle)$, and think of the operators A_n as matrices, relative to this basis. Now, A_n can be factored into polar form, $A_n = U_n P_n$, where P_n is positive self-adjoint and U_n is orthogonal. The fact that P_n is diagonalizable by orthogonal matrices implies that $A_n = V_n D_n W_n$ where D_n is diagonal, and V_n and W_n are orthogonal. Passing to a subsequence, if necessary, it may be assumed that one entry of D_n tends to infinity as $n \to \infty$. Modifying V_n if necessary, it may be assumed that it is the first entry, α_n^{-1} , which does so. Then $\alpha_n \to 0$. Since the orthogonal group is compact, it may be assumed that W_n converges to an orthogonal matrix W. Set $v_n = W_n \lambda_n$. We have $A_n W_n^{-1}(v_n) = A_n \lambda_n \to \mu$ and $v_n \to W \lambda = v$, also full. Replacing λ_n and A_n by v_n and $A_n W_n^{-1}$, we see that it may be assumed that A_n can be factored into the form

 V_nD_n , V_n orthogonal and D_n diagonal. Let $\varepsilon > 0$ be given: let $\Delta_r = \{x \mid ||x|| \le r\}$ and let r be chosen so large that

- (iii) $\lambda_n(\Delta) > 1 \varepsilon/2$ for all n,
- (iv) $A_n \lambda_n(\Delta) > 1 \varepsilon/2$ for all n,
- (v) Δ is a continuity set for λ and μ (i.e. $\lambda(bdry \Delta) = \mu(bdry \Delta) = 0$).

Now,
$$A_n^{-1}(\Delta) = D_n^{-1}V_n^{-1}(\Delta) = D_n^{-1}(\Delta)$$
, so by (iii) and (iv),

$$\lambda_n(D_n^{-1}(\Delta) \cap \Delta) > 1 - \varepsilon$$
 for all n ,

and

$$\lambda_n(D_n^{-1}(\Delta)) \to \mu(\Delta) > 1 - \varepsilon.$$

Notice that $x \in D_n^{-1}(\Delta) \cap \Delta$ implies $||x|| \le r$ and $||D_n x|| \le r$ so that $|x_j| \le r$ for $j = 2, \ldots, d$ and $|x_1| \le r\alpha_n$. Let L_n be the rectangle

$$\{x \mid |x_1| \le \alpha_n r, |x_j| \le r \text{ for } j = 2, \ldots, d\}.$$

Then $D_n^{-1}(\Delta) \cap \Delta \subseteq L_n$. Define $f_K(x) = \max [(1 - K|x_1|, 0)], K > 0$. We have

$$\int_{V} f_{K}(x) \lambda_{n}(dx) \geq \int_{L_{n}} f_{K}(x) \lambda_{n}(dx)$$

$$\geq \min \{ f_{K}(x) \mid x \in L_{n} \} \cdot \lambda_{n}(L_{n})$$

$$\geq \lambda_{n}(D_{n}^{-1}(\Delta) \cap \Delta) \cdot (1 - K\alpha_{n}r)$$

$$> (1 - \varepsilon)(1 - K\alpha_{n}r) \quad \text{for all } n, K > 0.$$

Letting $n \to \infty$, we find that $\int_V f_K(x) \lambda(dx) \ge 1 - \varepsilon$ for all K > 0, hence

$$\lambda\{x \mid |x_1| \ge 1/K\} \ge 1-\varepsilon$$
 for all $K > 0$,

implying $\lambda \{x \mid x_1 = 0\} \ge 1 - \varepsilon$. Since $\varepsilon > 0$ is arbitrary, $\lambda \{x \mid x_1 = 0\} = 1$ and λ must be deficient. This contradiction implies the truth of (B).

The proof of (A) now proceeds as follows: by assumption, $\{A_n\lambda_n*\delta(a_n)\}$ is precompact, and since (B) is true, $\{A_n\lambda_n\}$ is precompact; there is therefore a compact subset C of V such that $A_n\lambda_n(C) > 3/4$ and $(A_n\lambda_n*\delta(a_n))(C) > 3/4$ for all n, so that $A_n\lambda_n(C \cap (C-a_n)) > 1/2$ and certainly $C \cap (C-a_n) \neq \emptyset$; we conclude that for all n, $|a_n| \leq \text{diam } C < \infty$, and (A) is proven.

COROLLARY 1. If λ is any full measure in $\mathcal{P}(V)$ and if we define Inv $\lambda = \{(A, a) \in \text{Aff } V \mid A\lambda * \delta(a) = \lambda\}$, then Inv λ is a compact subgroup of Aff V.

COROLLARY 2. In the open subsemigroup \mathcal{F} of full measures in $\mathcal{P}(V)$, the relation " \sim " induces compact equivalence classes.

Both of these corollaries follow trivially from the compactness lemma.

6. A characterization of operator-stable measures. The class \mathcal{S} will now be characterized in a manner more amenable to analysis than that of the original definition.

THEOREM 1. A full measure $\mu \in \mathcal{P}(V)$ is stable (i.e., $\mu \in \mathcal{S}$) if and only if for each integer $n \ge 1$, there is an affine transformation (B_n, b_n) such that $\mu^n = B_n \mu * \delta(b_n)$. In other words, μ is in \mathcal{S} if and only if μ is full and all powers of μ are of the same type.

Proof. Firstly, if all powers of μ are of the same type, then for each n,

$$\mu = C_n \mu^n * \delta(c_n), \qquad (C_n, c_n) \in \text{Aff } V$$

so $\mu = \lim C_n \mu^n * \delta(c_n)$ implying $\mu \in S$.

Suppose now that μ is full and that

(i) $\mu = \lim A_n \lambda^n * \delta(a_n), \ \lambda \in \mathcal{P}(V), \ (A_n, a_n) \in \text{Aff } V.$

Since convolution is a jointly continuous operation, we obtain from (i) the equation

$$\mu^m = \lim_n \left[A_n \lambda^n * \delta(a_n) \right]^m \quad \text{for } m = 1, 2, \dots$$

and A_n being an automorphism of $\mathcal{P}(V)$, this last equation means

(ii)
$$\mu^m = \lim_n A_n \mu^{mn} * \delta(m \cdot a_n)$$
.

Taking the arithmetic subsequence $\{nm \mid n=1, 2, \ldots\}$ of $\{n \mid n=1, 2, \ldots\}$, we obtain from (i) that

(iii)
$$\mu = \lim_n A_{nm} \mu^{nm} * \delta(a_{nm})$$
.

Let
$$\mu_n = A_{nm} \lambda^{nm} * \delta(a_{nm})$$
. By (iii),

(iv)
$$\mu_n \rightarrow \mu$$
.

Equation (ii) can now be written

(v)
$$C_n\mu_n * \delta(c_n) \rightarrow \mu^m$$

where $C_n = A_n A_{nm}^{-1}$ and $c_n = m \cdot a_n - A_n A_{nm}^{-1} a_{nm}$. Since μ and μ^m are full measures, the compactness lemma can be invoked to infer from (iv) and (v) that μ and μ^m are of the same type, for every positive integer n.

Our next aim is to extend the last theorem to include all real positive powers of μ . In so doing, we get more information about the affine transformations which appear.

Theorem 2. If μ is full and operator-stable, there is an automorphism B of V such that

$$\mu^t = \exp \{ \log t \cdot B \} \mu * \delta(b(t)); \quad t > 0,$$

for some $b(t) \in V$. The converse is clearly true.

While the proof is not at all difficult, it involves many steps, and for better organization, we proceed with a sequence of simple lemmas. To start with, define $G_t = \{A \in \text{Aut } V \mid \mu^t = A\mu * \delta(a) \text{ for some } a \in V\}$. The set G_t may, a priori, be empty for some t > 0, but the last theorem shows that G_t is nonempty whenever t is a positive integer.

LEMMA 1.
$$G_t \neq \emptyset$$
 for any $t > 0$.

Proof. If t > 0 is rational and equal to j/k, G_j and G_k are nonempty and μ^j and μ^k are of the same type. Therefore, there is an affine transformation (B, b) such that

 $\mu^j = B\mu^k * \delta(b)$. But then, $(B\mu * \delta(1/k \cdot b))^k = \mu^j$, and so $B\mu * \delta(1/k \cdot b)$ is the unique infinitely divisible kth root of μ^j , so $B\mu * \delta(1/k \cdot b) = \mu^{j/k} = \mu^t$. Thus, $G_t \neq \emptyset$ if t is rational, and μ^t is of the same type as μ if t is rational. If t is any positive real number, let t_n be rational, and let $t_n \to t$. Then $\mu^{t_n} \to \mu^t$ and, if

$$\mu = C_n \mu^{t_n} * \delta(c_n), \qquad (C_n, c_n) \in \text{Aff } V,$$

the compactness lemma implies that μ^t is of the same type as μ , so that $G_t \neq \emptyset$.

LEMMA 2.
$$G_t^{-1} = G_{1/t}$$
 and $G_{s \cdot t} = G_s \cdot G_t$ for all $s, t > 0$.

Proof. It is easy to see that $G_t^{-1} \subset G_{1/t}$ and $G_s \cdot G_t \subset G_{st}$. Replacing t by 1/t in the first inclusion and s and t by 1/s and st in the second, the reverse inclusions hold.

LEMMA 3.
$$G_s \cap G_t = \emptyset$$
 if $s \neq t$.

Proof. If $A \in G_s \cap G_t$, say $\mu^s = A\mu * \delta(a)$ and $\mu^t = A\mu * \delta(a')$, then ${}^{\circ}\mu^s = {}^{\circ}\mu^t$ implying $|\mu^{\wedge}(y)|^{2s} \equiv |\mu^{\wedge}(y)|^{2t}$ for all y. If $s \neq t$, this implies that $|\mu^{\wedge}(y)| = 0$ or 1, so $|\mu^{\wedge}(y)| \equiv 1$, μ^{\wedge} being continuous. But this would mean that μ is degenerate.

LEMMA 4.
$$G = \bigcup \{G_t \mid t > 0\}$$
 is a closed subgroup of Aut V.

Proof. That G is a subgroup is the content of Lemma 2. To prove that G is closed in Aut V, let us assume that a sequence $\{A_n\}$ of members of G converges in Aut V to an automorphism A. We must show $A \in G$. Suppose $A_n \in G_{t_n}$. If $\{t_n\}$ contains a subsequence which converges to 0 in R it may be assumed for the purposes of this argument that $t_n \to 0$. Then $A_n\mu = \mu^{t_n} * \delta(a_n)$ for some $a_n \in V$, so $A_n({}^{\circ}\mu) = ({}^{\circ}\mu)^{t_n} \to \delta(0)$ as $n \to \infty$. Thus, $A({}^{\circ}\mu) = \delta(0)$, and since ${}^{\circ}\mu$ is full, A = 0, a contradiction which establishes the fact that $\{t_n\}$ cannot have a subsequence tending to 0. On the other hand, if t_n has a subsequence tending to ∞ , by setting $B_n = A_n^{-1} \in G_{1/t_n}$, $B_n \to A^{-1}$ and $1/t_n \to 0$. The last argument implies that $A^{-1} = 0$. We conclude that $\{t_n\}$ must be bounded away from 0 and ∞ . Let t be any limit point of $\{t_n\}$; it may be assumed that $t_n \to t$. Then $A_n\mu \to A\mu$ but

$$A_n\mu = \mu^{t_n} * \delta(a_n)$$
 and $\mu^{t_n} \to \mu^t$.

Since $A\mu$ and μ are full, the compactness lemma implies $\{a_n\}$ is precompact in V, so if a is any limit point, we have

$$A\mu = \mu^t * \delta(a)$$
, so that $A \in G_t \subseteq G$.

LEMMA 5. The mapping $\eta: G \to R^+$, defined by $\eta(A) = t$ if $A \in G_t$, is well defined, and is a continuous open homomorphism of G onto the positive reals under multiplication. The kernel of η is G_1 , a compact normal subgroup of G.

Proof. The mapping η is well defined by Lemma 3. It is a homomorphism because of Lemma 2. To prove that η is continuous, suppose $A_n \to A_0$ in G, with

 $\eta(A_n) = t_n$, so that $A_n \in G_{t_n}$. We have $\mu^{t_n} = A_n \mu * \delta(a_n)$ for some $a_n \in V$, so $({}^{\circ}\mu)^{t_n} = A_n({}^{\circ}\mu) \to A_0({}^{\circ}\mu) - ({}^{\circ}\mu)^{t_0}$. But this means $|\mu^{\wedge}(y)|^{2t_n} \to |\mu^{\wedge}(y)|^{2t_0}$, hence $t_n \to t_0$. The openness of η is now an automatic consequence of its continuity and the σ -compactness of G—see, e.g. Theorem 5.29 of Hewitt and Ross [2].

It remains only to show that B is invertible, if μ is full. If B were noninvertible, B^* would be noninvertible and there would exist $y \in V^{\wedge}$ such that $B^*y = 0$, $y \neq 0$. In this case, exp $\{\log t \cdot B^*\}_{y=y}$ for all t > 0, implying

$$|\mu^{t}(sy)| = |\mu^{t}(\exp \{\log t \cdot B^{*}\}sy)| = |\mu^{t}(sy)|.$$

This would mean $|\mu^{\hat{}}| \equiv 1$ on the subspace generated by y, a contradiction to the fullness of μ , by Proposition 1.

REMARK. We shall denote exp $\{\log t \cdot B\}$ by the notation t^B .

7. The class \mathcal{B} . The class of operators, B, which can occur in a representation $u^t = t^B \mu * \delta(b(t))$ for some full measure μ will be denoted by \mathcal{B} . So far, we know only that \mathcal{B} consists solely of nonsingular operators. It is easy to check, now, that if $B \in \mathcal{B}$ and A is any automorphism, $ABA^{-1} \in \mathcal{B}$. In other words, \mathcal{B} is closed under similarity transformations, and \mathcal{B} will be describable through spectral properties. In fact,

Theorem 3. Necessary and sufficient conditions for an operator B to be in the class \mathcal{B} are

- (i) The spectrum of B is in the half-plane Re $z \ge 1/2$, and
- (ii) The eigenvalues lying on the line Re z = 1/2 are simple—i.e. the elementary divisors of B associated with these eigenvalues are of first degree.

Once again, the rather complicated proof obliges us to break it down to more organizable parts. Firstly, we record some facts about the representing triple of a stable distribution.

PROPOSITION 5. If $\lambda \in S$ has representing triple (c, ϕ, M) and $\lambda^t = t^B \lambda * \delta(b(t))$, $B \in \mathcal{B}$, then

- (a) $\phi(t^{B^*}y) = t\phi(y)$ for $y \in V^{\wedge}$ and t > 0,
- (b) $t^B M = tM$ for t > 0.

Proof. A direct application of Theorem 2 on Proposition 3. The heart of the proof of Theorem 3 lies in

LEMMA 6. A measure M concentrated on an orbit $\{t^Bx_0 \mid t>0\}$ and satisfying $t^BM=tM$ is a K-L measure if and only if every eigenvalue of B in the cyclic subspace generated by x_0 has real part greater than 1/2.

Proof. Assume firstly that $S(M) \subset \{t^B x_0 \mid t > 0\}$ and $t^B M = tM$. Let $X = [x_0, Bx_0, B^2 x_0, \dots] = [x_0]$, the cyclic subspace generated by x_0 . Since B is non-singular, BX = X, and since our interest is only in the behavior of B on X, we assume $B = B \mid X$. B is then a cyclic operator, and by structure theory for such operators (see, e.g. Jacobson [3, p. 73]), to each elementary divisor of B, there is a subspace X_i , such that

- (i) $BX_i = X_i$, and
- (ii) $X = X_1 \oplus \cdots \oplus X_k$.

Also, the minimum polynomial $q_j^{m_j}$ of $B|X_j$ is a power of a polynomial which is irreducible over the real field.

Now, set $F(s) = M\{t^Bx_0 \mid t > s\}$. The condition $t^BM \equiv tM$ implies that F(st) = 1/tF(s). Thus, F(t) = K/t for some constant K > 0. The measure M is a K-L measure if and only if $\int ||x||^2 M(dx) < \infty$ in a neighborhood of 0. This is the case if and only if

$$\int_0^1 \|t^B x_0\|^2 (-dF/dt) \, dt < \infty,$$

or

$$\int_0^1 \|t^B x_0\|^2 t^{-2} dt < \infty.$$

Here, $\|\cdot\|$ is any vector norm on X. Any other vector norm would suffice, for all such norms are equivalent on X. We shall specify a norm on X which facilitates computation. Let $\|\cdot\|_j$ be a vector norm on X_j , to be chosen later, and let $\|\sum x_j\| = \sum \|x_j\|_j$. Then $\|\cdot\|_j$ is a norm on X with the property that $\|\sum x_j\| \ge \|x_r\|_r$ for each r, $1 \le r \le k$. Suppose $x_0 = \sum_{j=1}^k x_j$, $x_j \in X_j$. Then $x_j \ne 0$ for each j, otherwise x_0 fails to be cyclic in X. We have then $t^B x_0 = \sum_{j=1}^k t^B x_j = \sum_{j=1}^k t^B x_j$, where $B_j = B|X_j$, and $\|t^B x_0\| \ge \|t^B r_j x_r\|_r$, for each r. For the rest of the proof, let r be arbitrary but fixed, $1 \le r \le k$. We now choose $\|\cdot\|_r$ in X_r as follows: extend X_r to its complexification X_r^c , and let B_r^c be the extension of B_r to X_r^c in the usual way. We shall define a norm $\|\cdot\|_r^c$ for X_r^c and let $\|\cdot\|_r$ be the restriction of $\|\cdot\|_r^c$ to X_r . For notational convenience, let $J(a_1, \ldots, a_k)$ denote the $k \times k$ matrix having all entries equal to zero below the diagonal, a_1 on the principal diagonal, a_2 on the super-diagonal,

..., a_k in (1, k) position. To choose $\|\cdot\|_r^c$, let us firstly choose a (complex) basis $\{\xi_1, \ldots, \xi_p\}$ for X_r^c so that the matrix of B_1^c with respect to $\{\xi_1, \ldots, \xi_p\}$ is $J(\alpha, 1, 0, \ldots, 0)$ if q_j is linear, and

$$\begin{pmatrix} J(\alpha, 1, 0, \dots, 0) & 0 \\ 0 & J(\bar{\alpha}, 1, 0, \dots, 0) \end{pmatrix}$$

if q_j is quadratic. The complex numbers α , $\bar{\alpha}$ are the eigenvalues of B_j , hence of B_j . Choose $\|\cdot\|_r^c$ by making $\|\sum \alpha_j \xi_j\|_r^c = \sum |\alpha_j|$. Then, we have $\|t^{B_r}X_r\|_r = \|t^{B_r}X_r\|_r^c$, and since the (complex) matrix of t^{B_r} can be seen by an easy computation to be

$$J(t^{\alpha}, t^{\alpha} \log t, ..., 1/(p-1)! t^{\alpha} (\log t)^{p-1})$$

if q_j is linear, or the obvious extension if q_j is quadratic, $(\|t^{B_r}x_r\|_r^c)^2$ is seen to be a linear combination, with coefficients depending on x_r , of terms of the form $t^{\alpha}(\log t)^m t^{\bar{\alpha}}(\log t)^n$, $m \le p-1$, $n \le p-1$, and these terms are each $t^{2\operatorname{Re}\alpha}(\log t)^q$, for some $q \le 2p-2$. Then

$$\int_0^1 \|t^{B_r} x_r\|^2 t^{-2} dt \ge \int_0^1 \text{const } t^{2 \operatorname{Re} \alpha} t^{-2} dt$$

$$\ge \operatorname{const} \int_0^1 t^{2 \operatorname{Re} \alpha - 2} dt.$$

The first term is finite, by (*), so 2 Re $\alpha - 2 > -1$, implying Re $\alpha > 1/2$.

To obtain the converse, note that Re $\alpha > 1/2$ implies $\int_0^1 t^{2\operatorname{Re}\alpha - 2} dt < \infty$ and an integration by parts shows that all the terms $t^{\alpha}(\log t)^m t^{\overline{\alpha}}(\log t)^n$, as above, have finite integrals at 0. Taking the same norms as above, we find

$$\int_0^1 \|t^{B_r} x_r\|_r^2 t^{-2} dt < \infty,$$

so

$$\int_0^1 \|t^B x\|^2 t^{-2} dt \le \text{const } \Sigma_\tau \int_0^1 \|t^{B_\tau} x_\tau\|^2 t^{-2} dt < \infty.$$

We now proceed with the

Proof of Theorem 3. Let $\Lambda(B) = \{M \mid M \text{ a K-L measure on } V \sim \{0\} \text{ and } t^B M = tM\}$. Note that if $M \in \Lambda(B)$, S(M) is invariant under t^B for all t > 0, so that S(M) is a union of orbits of t^B . The M may be infinite measures, but they are essentially finite in the sense that $W(dx) = ||x||^2/(1 + ||x||^2)M(dx)$ is a finite measure in V. To apply the theory of finite measures, let $\mathfrak{M}(V)$ be the real linear space of finite measures in V, with the topology of weak convergence. Let

$$\Omega(B) = \{ W \in \mathfrak{M}(V) \mid W(dx) = \|x\|^2 / (1 + \|x\|^2) M(dx), M \in \Lambda(B) \}.$$

 $\Omega(B)$ is easily seen to be a convex cone in \mathfrak{M} , and $\Omega_1(B) = \{W \in \Omega \mid W(V) \leq 1\}$ is a compact convex subset of \mathfrak{M} . Each W in Ω has the property that S(W) is a union of orbits of t^B . Thus, it is easily seen that the extreme points of $\Omega_1(B)$ are the

measures concentrated along a single orbit $\{t^Bx_0 \mid t>0\}$. Thus, the set of convex combinations of such measures is dense in Ω_1 , and this shows that in $\Lambda(B)$, the linear combinations of M's which are concentrated in a single orbit are dense in $\Lambda(B)$.

Let X now be decomposed into a direct sum of subspaces X_j $(1 \le j \le r)$ such that $BX_j = X_j$, and such that the minimum polynomial of $B|X_j$ is a power of a real-irreducible polynomial. Assume that the eigenvalues in X_1, \ldots, X_k lie in Re z > 1/2 and those in X_{k+1}, \ldots, X_r lie in Re $z \le 1/2$. Let $X_0 = X_{k+1} + \cdots + X_r$. Now, if $x \in X$, and $x = \sum_{i=0}^k x_i$, $x_i \in X_j$ then, by Lemma 6, the orbit $\{t^B x \mid t > 0\}$ supports a nonzero K-L measure $M \in \Lambda(B)$ if and only if $x_0 = 0$. Hence, since linear combinations of such M are dense in $\Lambda(B)$, M is concentrated in $X_1 + \cdots + X_k$, for all $M \in \Lambda(B)$.

To find how B behaves in X_0 , examine the adjoint $B^*: V^{\wedge} \to V^{\wedge}$. Let, in V^{\wedge} ,

$$Y_j = (X_0 \oplus \cdots \oplus X_{j-1} \oplus X_{j+1} \oplus \cdots \oplus X_k)^{\perp}, \quad 0 \le j \le k.$$

 Y_j is then the dual of X_j , and $B^*|Y_j=(B|X_j)^*$. It is a consequence of the Khintchine-Lévy formula that

$$\log {^{\circ}\mu}(y) = -2\phi(y) + \int (\cos(x, y) - 1)M(dx)$$

and if $y \in Y_0$, since M is concentrated in $X_1 \oplus \cdots \oplus X_k$,

$$\log^{\circ}\mu^{\wedge}(y) = -2\phi(y).$$

Since μ is assumed full, $\phi(y) \neq 0$ if $y \in Y_0$, $y \neq 0$. Thus, the quadratic form $\phi \mid Y_0$ is nondegenerate, and there is a basis $\{y_1, \ldots, y_q\}$ in Y_0 such that

$$\phi\left(\sum_{1}^{q} a_j y_j\right) = \sum_{1}^{q} a_j^2.$$

With respect to this basis $\{y_1, \ldots, y_q\}$, a bilinear form $\langle \cdot, \cdot \rangle$ is defined, and adjoints C' of operators C are defined by

$$\langle Cy_1, y_2 \rangle = \langle y_1, C'y_2 \rangle.$$

Then, the condition 5(a) reads that for all $y \in Y_0$ and t > 0,

$$\phi(t^{B*}y) = t\phi(y).$$

Since $B^*Y_0 = Y_0$, it will not hurt to assume in this section that $B^* = B^* | Y_0$. Then, for all $y \in Y_0$,

$$\langle t^{B*}v, t^{B*}v \rangle = t \langle v, v \rangle.$$

Thus,

$$\langle t^{B*}t^{B*'}y, y \rangle = \langle ty, y \rangle$$

or

$$t^{B^*}t^{B^{*'}} \equiv tI \equiv t^{1/2}I \cdot t^{1/2}I.$$

Since $t^{1/2}I \equiv t^{1/2}$, this can be written as

$$t^{(B^*-I/2)}t^{(B^*-I/2)'} = I$$

Setting $C=B^*-I/2$, we find that $t^{C+C'}\equiv I$ for all t>0, so that C+C'=0. Thus, in this basis, C is a skew operator. Hence $B^*=I/2+C$ is a normal operator, and all its elementary divisors are linear. This proves the necessity of the conditions in the theorem. To prove the sufficiency of the conditions, let B satisfy (i) and (ii). As in the proof of the necessity, let $X=X_1\oplus\cdots\oplus X_r$, X_j having the same meaning as before. If $x_j\in X_j$, $x_j\neq 0$, $(1\leq j\leq k)$, then, by Lemma 6, the orbit $\{t^Bx_j\mid t>0\}$ supports a nonzero K-L measure $M_j\in \Lambda(B)$. Since the orbit $\{t^Bx_j\mid t>0\}$ generates X_j , the stable measure λ_j with triple $(0,0,M_j)$ is supported, and is full, in X_j . On $X_0=X_{k+1}\oplus\cdots\oplus X_r$, we construct a Gaussian measure μ satisfying $\mu^t=\exp\{\log t\cdot B\mid X_0\}\mu$. We can imagine that $X=X_0$, hence that B may be put into a canonical form diag $\{J_1,\ldots,J_q\}$ where J_j is either a 1×1 matrix with element 1/2, or a 2×2 matrix

$$\begin{pmatrix} 1/2 & \beta \\ -\beta & 1/2 \end{pmatrix}$$
.

With the dual basis $\{\eta_1, \ldots, \eta_p\}$ in Y_0 , B^* has canonical form diag $\{J_1^*, \ldots, J_q^*\}$. We have to construct a quadratic form ϕ on Y_0 such that $\phi(t^{B^*}y) \equiv t\phi(y)$. Consider $\phi(\sum a_i\eta_i) = \sum a_i^2$. If $[\eta_1] = X_j$, $t^{J_j} = t^{1/2}I$ and $\phi(t^{J_j}a\eta_i) = t\phi(a\eta_i)$. If $[\eta_i, \eta_{i+1}] = X_j$, we have

$$t^{J_j} = t^{1/2} \begin{pmatrix} \cos(\beta \log t) & \sin(\beta \log t) \\ -\sin(\beta \log t) & \cos(\beta \log t) \end{pmatrix}$$

and, once again, $\phi(t^{J_j}(a\eta_i+b\eta_{i+1}))=t\phi(a\eta_i+b\eta_{i+1})$. Thus, $e^{-\phi(y)}$ is a Gaussian characteristic function, and its distribution is full and concentrated in X_0 . The measure $\nu=\lambda_1*\cdots*\lambda_k*\mu$ is now full and stable, and $\nu^t=t^B\nu$.

As by-products of the proof of Theorem 3, we can assert the following:

THEOREM 4. Any full operator-stable measure λ on V can be decomposed into a product $\lambda = \lambda_1 * \lambda_2$ of measures λ_i concentrated in subspaces V_i , $V = V_1 \oplus V_2$, where λ_1 is a full Gaussian measure in V_1 and λ_2 is a full operator-stable measure on V_2 having no Gaussian component.

THEOREM 5. Any K-L measure M for a full operator-stable measure λ on V can be represented as a mixture of K-L measures M_{θ} where M_{θ} is a K-L measure concentrated in an orbit, θ , of t^B and satisfies $t^BM_{\theta} = tM_{\theta}$. The measure M_{θ} is characterized by the condition that $sM_{\theta}\{t^Bx_0 \mid t>s\}$ is constant for all s, when x_0 is a generator of the orbit θ .

If λ is full and operator-stable, and satisfies $\lambda^t = t^B \lambda * \delta(b(t))$ for some b(t), we shall call B an exponent for λ . A measure λ may possess more than one exponent. For example, if V is given an inner product with respect to which λ is a rotation-invariant Gaussian measure, then B = I/2 is an exponent for λ , as is any operator of the form I/2 + C where C is skew.

The operators in the class \mathcal{B} can be interpreted as exponents of the normalizing factors which give rise to operator-stable laws. That is, if x_1, x_2, \ldots are independent

full operator-stable random variables having the same distribution, then each has the same distribution as some translate of $n^{-B}(x_1 + \cdots + x_n)$, for $n = 1, 2, \ldots$

8. Centering. We turn, finally, to an examination of the term b(t) in the formula

(8.1)
$$\lambda^t = t^B \lambda * \delta(b(t)) \text{ for all } t > 0,$$

satisfied by a full operator-stable measure λ with exponent B. Taking sth powers on both sides of (8.1), we find that

$$\lambda^{st} = t^B \lambda^s * \delta(sb(t)) = t^B s^B \lambda * \delta(t^B b(s) + sb(t)).$$

But $\lambda^{st} = (st)^B \lambda * \delta(b(st))$, from (8.1), so that the vector-valued function $b(\cdot)$ must satisfy the functional equation

(8.2)
$$b(st) = t^B b(s) + sb(t)$$
 for all $s > 0, t > 0$.

One consequence, obtained by setting s=t=1, is that b(1)=0.

THEOREM 6. If 1 is not in the spectrum of B, the general solution of (8.2) is

$$(8.3) b(t) = tx_0 - t^B x_0, t > 0,$$

for some $x_0 \in V$, and in this case, when the full operator-stable measure λ satisfying (8.1) is centered at x_0 , the measure $\mu = \lambda * \delta(-x_0)$ satisfies $\mu^t = t^B \mu$.

REMARK. By analogy with the one-dimensional case, an operator-stable measure μ satisfying $\mu^t = t^B \mu$ could be called strictly stable. Our theorem shows that when 1 is not in the spectrum of B, any full operator-stable measure can be centered so as to become strictly stable.

Proof. Once we have proven (8.3), the second assertion of the theorem follows by a standard calculation. As a first step in proving (8.3), note that if $b_1(\cdot)$ and $b_2(\cdot)$ are solutions of (8.2), then $b_1(\cdot) - b_2(\cdot)$ is a solution of (8.2). Note also that if $b(\cdot)$ is a solution of (8.2) such that $b(t_0) = 0$ for some $t_0 \neq 1$, then

$$b(st_0) = t_0b(s) = t_0^Bb(s)$$
 for all $s > 0$.

Since 1 is not an eigenvalue of B, t_0 is not an eigenvalue of t_0^B , so we must have $b(s) \equiv 0$. These observations imply that any two solutions of (8.2) which agree at even one point must in fact be identical.

Now, the operator $(tI-t^B)$ is invertible, for $t \neq 1$, hence we can always solve an equation

$$(tI-t^B)x_0 = x_1$$
 for $x_0 \in V$, for all $x_1 \in V$.

Hence, the solutions $b(t) = tx_0 - t^B x_0$ constitute all possible solutions of (8.2).

In the event that B has 1 as an eigenvalue, it may not be possible to center λ as in the last theorem. This is in analogy with the one-dimensional case of the so-called asymmetric Cauchy distribution. An example is given by taking B=I so that (8.2) becomes

$$b(st) = sb(t) + tb(s)$$
,

which is satisfied by the function $b(t) = t \log tx_0$, for all $x_0 \in V$. We can clearly not absorb such a factor to center λ .

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